

STRESSED STATE OF FERROMAGNETIC PLATE WITH CRACKS IN THE PRESENCE OF STRONG MAGNETIC FIELD

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If a ferromagnetic body is placed in a magnetic field, body and surface forces appear in the body due to the magnetizability of a material. Under the action of these forces deformations that alter the initial magnetic field appear in the medium.

In the present work we consider a boundary value problem of magnetoelasticity for magnetically soft ferromagnetic medium, weakened by curvilinear cracks. We assume that there is a constant magnetic field \mathbf{H}_0 and normal and tangent forces are given on the edges. A similar problem for an isolated straight crack was considered in [1, 2].

1. In linearized statement [1, 3] a complete system of magnetoelasticity relations for magnetically soft piecewise equations of state

$$\begin{aligned} \mathbf{B} &= \mu_0 \mu_r \mathbf{H}, \quad \mathbf{b} = \mu_0 \mu_r \mathbf{h}, \quad \mathbf{M} = \chi \mathbf{H}, \quad \mathbf{m} = \chi \mathbf{h}, \\ \mathbf{H} &= \mathbf{H}_0 + \mathbf{h}, \quad \mathbf{B} = \mathbf{B}_0 + \mathbf{b}, \quad \mathbf{M} = \mathbf{M}_0 + \mathbf{m} \end{aligned} \quad (1.1)$$

and magnetoelasticity differential equations

$$\begin{aligned} \operatorname{div} \mathbf{S} &= 0, \quad \operatorname{rot} \mathbf{H}_0 = 0, \quad \operatorname{div} \mathbf{B}_0 = 0, \quad \operatorname{rot} \mathbf{h} = 0, \quad \operatorname{div} \mathbf{b} = 0, \\ \mathbf{S} &= \mathbf{T} + \mathbf{t}, \quad t_{ij} = \sigma_{ij} + \mu_0 \chi H_{0i} H_{0j} + \mu_0 \chi (H_{0i} h_j + H_{0j} h_i), \\ T_{ij} &= \mu_0 (\mu_r H_{0i} H_{0j} - 0.5 \delta_{ij} H_{0k} H_{0k}) + \mu_0 [\mu_r (H_{0i} h_j + H_{0j} h_i) - \delta_{ij} H_{0k} h_k], \\ \sigma_{ij} &= \lambda \delta_{ij} \partial_k u_k + \mu (\partial_j u_i + \partial_i u_j), \quad \partial_k = \partial / \partial x_k. \end{aligned} \quad (1.2)$$

The boundary conditions in the media boundary line have the form

$$\begin{aligned} n_1 (b_1 - b_1^{(e)}) + n_2 (b_2 - b_2^{(e)}) &= \mu_0 \chi H_0 \cos \psi \cdot n_m \partial u_m / \partial s, \\ -n_2 (h_1 - h_1^{(e)}) + n_1 (h_2 - h_2^{(e)}) &= \chi H_0 \sin \psi \cdot n_m \partial u_m / \partial s, \\ n_1 (S_{1j} - S_{1j}^{(e)}) + n_2 (S_{2j} - S_{2j}^{(e)}) &= 0. \end{aligned} \quad (1.3)$$

In relations (1.1)-(1.3) $\mu_0 = 4\pi \cdot 10^{-7}$ H/m is the absolute magnetic constant; $\mu_r = 1 + \chi$ is a relative permeability of the medium; \mathbf{B}_0 , \mathbf{H}_0 , and \mathbf{M}_0 are the magnetic induction, initial magnetic field strength, and magnetization of the material; \mathbf{b} , \mathbf{h} , and \mathbf{m} are fluctuations of these quantities; u_k is the medium elastic displacement; λ and μ are the Lamé constants; δ_{ij} is the Kronecker delta; and ε_{ijk} is the Levi-Civita symbol.

Let an infinite magnetoelastic medium referred to $x_1 O x_2$ coordinate system be in a strong magnetic field $\mathbf{H}_0 = (0, H_0, 0)$. We assume that there are cracks in the medium, which in undistorted state are associated with mathematical cuts ($j = 1, \dots, k$). On the edges L_j we specify a normal and a tangent load N and T continuously extendible from one edge to the other.

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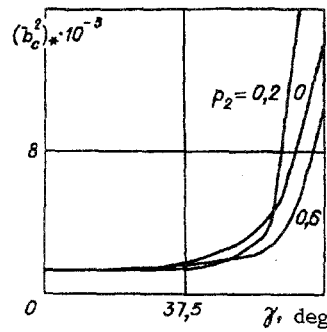


Fig. 1

In this statement the plane problem of magnetoelasticity being considered is reduced to the following system of differential equations:

$$\begin{aligned} \nabla^2 u_j + \sigma \partial_j \theta + \frac{2}{\mu} \chi \mu_0 H_0 \partial_2 h_j &= 0 \quad (j = 1, 2), \\ \nabla^2 U &= 0, \quad h_j = \partial_j U, \quad \nabla^2 = \partial_1^2 + \partial_2^2, \quad \sigma = (1 - 2\nu)^{-1}. \end{aligned}$$

The solutions of this system can be expressed in terms of three arbitrary analytic functions by the equations

$$\begin{aligned} 2\mu (u_1 + iu_2) &= \kappa \varphi(z) - zW(z) - \overline{\varphi_1(z)} - C_0 f(z), \\ t_{11} + t_{22} &= 2 \operatorname{Re} \Phi(z) + 2 \operatorname{Re} W(z) + C_0 H_0, \\ t_{22} - t_{11} + 2it_{12} &= 2\bar{z}W'(z) + 2W_1(z) + C_0, \\ h_1 - ih_2 &= iF(z), \quad F(z) = f'(z), \quad \Phi(z) = \varphi'(z), \\ \Phi_1(z) &= \varphi_1'(z), \quad \kappa = 3 - 4\nu, \quad W(z) = \Phi(z) - C_0 F(z), \\ W_1(z) &= \Phi_1(z) - C_0 F(z), \quad C_0 = \chi \mu_0 H_0. \end{aligned}$$

The boundary conditions on the cut edges are represented correspondingly. Taking into account (1.3), we can write them in a complex form

$$\begin{aligned} 2 \operatorname{Re} W(z) - \exp(2i\psi) \{ \bar{\zeta} W'(\zeta) + W_1(\zeta) \} + C_0 \Lambda^*(\zeta) &= R(\zeta), \\ \Lambda^*(\zeta) &= \operatorname{Re} \{ (1 - i\chi n_2 \exp(i\psi)) F(\zeta) \}, \\ R(\zeta) &= N - iT + C_0 H_0 (\chi n_2^2 - 1 + \exp(2i\psi)) / 2, \\ n_m \partial u_m / \partial s &= \operatorname{Im} \{ -\kappa \Phi(z) - W(z) + C_0 F(z) + \\ &+ \exp(2i\psi) (\bar{z} W'(z) + \Phi_1(z)) \} / 2\mu, \quad \zeta \in L_j. \end{aligned} \quad (1.4)$$

2. To solve the formulated boundary value problem let us introduce integral representations of the analytic functions:

$$\begin{aligned} F(z) &= \frac{C_0}{2\pi i} \int_L \frac{\omega(\zeta)}{\zeta - z} d\zeta, \quad W(z) = -\frac{1}{2\pi i} \int_L \frac{p(\zeta)}{\zeta - z} d\zeta, \\ W_1(z) &= \frac{1}{2\pi i} \int_L \frac{\zeta p(\zeta)}{(\zeta - z)^2} d\zeta + \frac{1}{2\pi i} \int_L \frac{\bar{q}(\bar{\zeta})}{\zeta - z} d\bar{\zeta}. \end{aligned}$$

Substitution of limiting values of these functions into boundary conditions (1.4) leads to a system of singular integral equations with respect to displacement jumps and their derivatives:

$$\begin{aligned} \int_L \{ U(\zeta) dH_{11}(\zeta, \zeta_0) + V(\zeta) dH_{12}(\zeta, \zeta_0) \} &= N_1(\zeta_0), \\ \int_L \{ U(\zeta) dH_{21}(\zeta, \zeta_0) + V(\zeta) dH_{22}(\zeta, \zeta_0) \} &= N_2(\zeta_0). \end{aligned} \quad (2.1)$$

Here

$$\begin{aligned}
dH_{11} &= \operatorname{Im} \left\{ [-h_1(\psi)(h_4(\psi_0)(\kappa+1) + h_3(\psi_0) \exp(2i(\psi - \alpha_0))/2) + \right. \\
&\quad \left. + h_2(\psi) h_3(\psi_0) \exp(2i(\psi - \psi_0))/2 - i\chi^2 \mu_0 e_0^2 (\kappa+1) \delta(\psi) h_5(\psi_0)/4] \frac{d\zeta}{\zeta - \zeta_0} \right\}; \\
dH_{12} &= \operatorname{Im} \left\{ [1 + \chi^2 (\kappa+1) i e_0^2 n_1^0 n_2^0 /4 + \right. \\
&\quad \left. + h_3(\psi_0) (\exp(2i(\psi_0 - \alpha_0)) - \exp(2i(\psi_0 - \psi)))/2] \frac{d\zeta}{\zeta - \zeta_0} \right\}; \\
dH_{21} &= \operatorname{Re} \left\{ [h_6(\psi_0)(h_1(\psi) \exp(2i(\psi_0 - \alpha_0)) - h_2(\psi) \exp(2i(\psi_0 - \psi)))/2 + \right. \\
&\quad \left. + \chi(1 + \chi \sin^2 \psi_0) e_0^2 (\kappa+1) h(\psi, \psi_0)/4] \frac{d\zeta}{\zeta - \zeta_0} \right\}; \\
dH_{22} &= \operatorname{Re} \left\{ [h_6(\psi_0) (\exp(2i(\psi_0 - \psi)) - \exp(2i(\psi_0 - \alpha_0)))/2 - \right. \\
&\quad \left. - \chi(\kappa+1) e_0^2 (1 + \chi \sin^2 \psi_0)/4] \frac{d\zeta}{\zeta - \zeta_0} \right\}; \\
N_1(\zeta) &= (\kappa+1) \pi [N/\mu + \chi e_0^2 (\chi n_2^2 + \cos 2\psi - 1)/2]/2; \\
N_2(\zeta) &= (\kappa+1) \pi [-T/\mu + \chi e_0^2 \sin 2\psi/2]/2; \\
h_1(\psi) &= i + e_0^2 \Lambda(\psi); \quad h_2(\psi) = e_0^2 \overline{\Lambda_1(\psi)} - i; \quad h_3(\psi) = \frac{\kappa-1}{\kappa+1} + 2h_4(\psi); \\
h_4(\psi) &= \frac{1}{\kappa+1} + \chi^2 i e_0^2 n_1 n_2 /4; \\
h_5(\psi) &= \overline{\alpha(\psi)} + \chi^2 e_0^2 n_1 n_2 (1 - \kappa + \exp(2i\psi))/2; \\
h_6(\psi) &= 1 + \chi e_0^2 (1 + \chi \sin^2 \psi)/2; \\
h(\psi, \psi_0) &= h_1(\psi) + \chi^2 \mu_0 e_0^2 \delta(\psi) (1 - \kappa + \exp(2i\psi_0))/2; \\
\Lambda(\psi) &= \chi \{i + \chi [in_1(2 - \kappa)/\mu_r - n_2(\kappa+1)] \exp(-i\psi)\}/2; \\
\Lambda_1(\psi) &= \chi \{-\kappa i + \chi i n_1(2 - \kappa) \exp(-i\psi)/\mu_r\}/2; \\
\alpha(\psi) &= \chi n_2 \exp(-i\psi) - i; \\
e_0^2 &= \mu_0 H_0^2 / \mu; \quad \zeta, \zeta_0 \in L_j.
\end{aligned}$$

System (2.1) should be considered together with the additional conditions

$$\int_{L_j} (U + iV) d\zeta = 0 \quad (j = \overline{1, k}). \quad (2.2)$$

To solve numerically the system of equations (2.1) and (2.2), it is convenient to carry out parametrization of the contour L_j (below we omit index j): $\zeta = \zeta(\beta)$, $\zeta_0 = \zeta(\beta_0)$, $-1 \leq \beta, \beta_0 \leq 1$. Following this we represent:

$$U(\zeta) = \frac{\Omega(\beta)}{\sqrt{1-\beta^2}}, \quad V(\zeta) = \frac{\Omega^*(\beta)}{\sqrt{1-\beta^2}}, \quad a = \zeta(-1), \quad b = \zeta(1).$$

Applying the known quadrature formulas [4], we reduce (2.1) and (2.2) to the system of linear algebraic equations with respect to the values of functions Ω and Ω^* in Chebyshev nodes.

Stress intensity coefficients are determined in the regular way and have the form

$$K_I - iK_{II} = \pm \mu \sqrt{s'(\pm 1)} \left\{ -2 \frac{\Omega - i\Omega^*}{\kappa+1} + \chi e_0^2 \Omega \left[\frac{\kappa-1}{\kappa+1} + \sum_{i,j=1}^2 a_{ij}^* n_i n_j \right] /2 \right\},$$

$$a_{11}^* = -1 - \frac{(2-\kappa)2\chi}{(\kappa+1)(\chi+1)}, \quad a_{22}^* = -(2\chi+1),$$

$$a_{12}^* = a_{21}^* = i\chi [1 - (2-\kappa)/(\kappa+1)(\chi+1)].$$

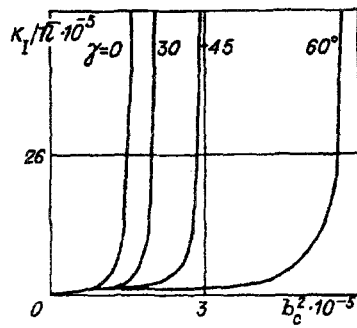


Fig. 2

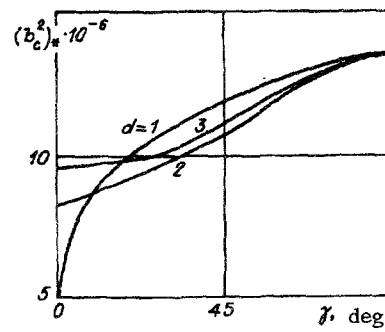


Fig. 3

3. As a first example let us consider the medium weakened by one parabolic crack $x_1 = p_1 \beta \cos \gamma - p_2 \beta^2 \sin \gamma$, $x_2 = p_1 \beta^2 \sin \gamma + p_2 \beta^2 \cos \gamma$ ($|\beta| \leq 1$) (γ is the angle of crack rotation with respect to the system of coordinates $x_1 O x_2$). From [1, 2] it follows that there are critical values of the parameter $b_c^2 = b_0^2 / \mu_0 \mu$, for which the stresses in the medium become infinitely large. For a straight crack, whose front is perpendicular to the direction of the initial magnetic field, $b_c^2 = 1.33 \cdot 10^{-5}$ (for $\nu = 0.25$ and $\chi = 10^5$). For another crack orientation with respect to the initial magnetic field the critical values will be different. The critical values of b_c^2 according to crack orientation γ for different values of the parabolic crack curvature are plotted in Fig. 1. The curves describing the deformation intensity coefficient K_I as a function of the parameter b_c^2 for different orientations of a straight crack are given in Fig. 2.

Let us consider the situation when the medium is weakened by two straight cracks, one of which occupies the interval $[-l; l] = [-1; 1]$ of the x_1 -axis and the other is turned to it through the angle γ . The distance between the centers of both cracks is $d = 1, 2, 3$ and the length of the second crack is $2l_1 = 2$. The critical values of b_c^2 as a function of the angle γ between the cracks, for different distances d between them are plotted in Fig. 3. It is seen that if the second crack is perpendicular to the first one, the value of b_c^2 is the same as for the medium with one crack perpendicular to the initial magnetic field. When both cracks are parallel, b_c^2 increases monotonically with the distance between them.

Analysis of the results shows that the initial magnetic field B_0 , whose level is close to the critical value, has a pronounced effect on the equilibrium of ferromagnetic medium with a straight crack. Thus, for a horizontal crack $B_0 \approx 1.2$ T. In the general case critical values of the initial magnetic field levels depend essentially on the mutual arrangement of the defects and their configuration.

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